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Where innovation starts



Aging-in-place

Automation in construction

Outline

Problem

Workforce & the Aging Society

Modeling activities from the perspective of robotization

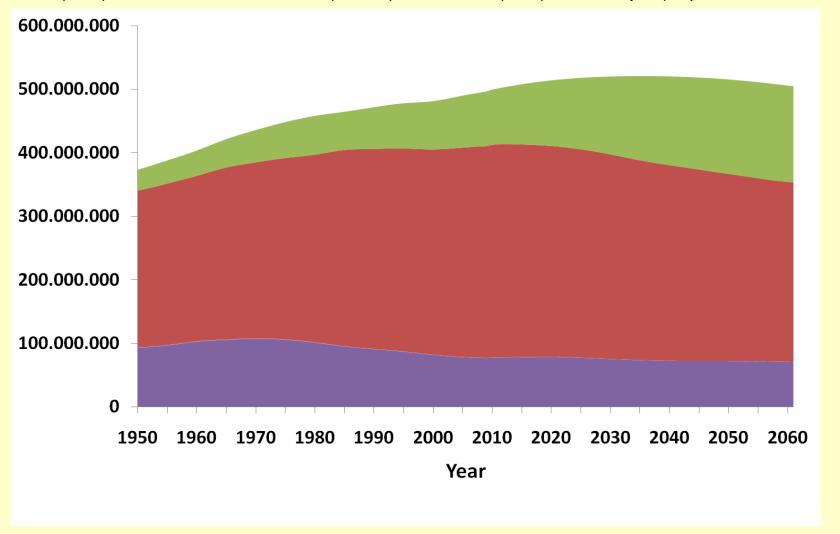
Solutions

Lessons from the construction industry

Working methods to enhance end-user values
Analysis activities
Design solutions

Workforce & Aging Society

Youth (<15) & Potential Workforce (15-65) & Retired (>65) for Europe (27) over 1950-2060



Daily activities in the house









Daily activities round the house

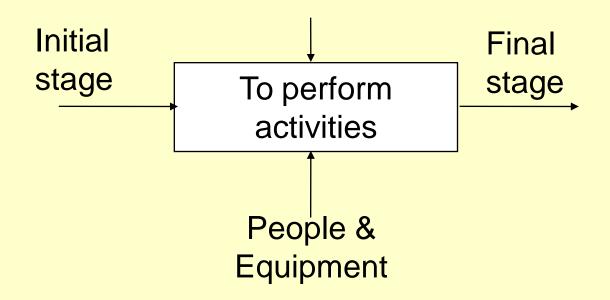






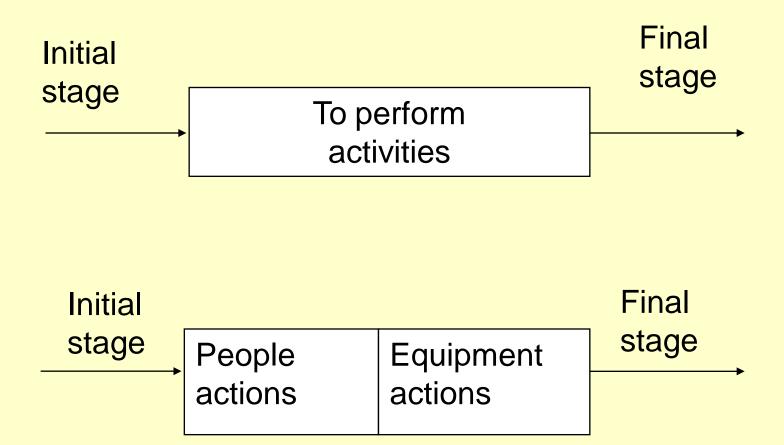


Modeling activities by SADT (Structured Analysis and Design Technique)



http://en.wikipedia.org/wiki/Structured_Analysis_and_Design_Technique

People and equipment actions



Activity aspects:

- Physical actions
- Mental actions
- Social actions



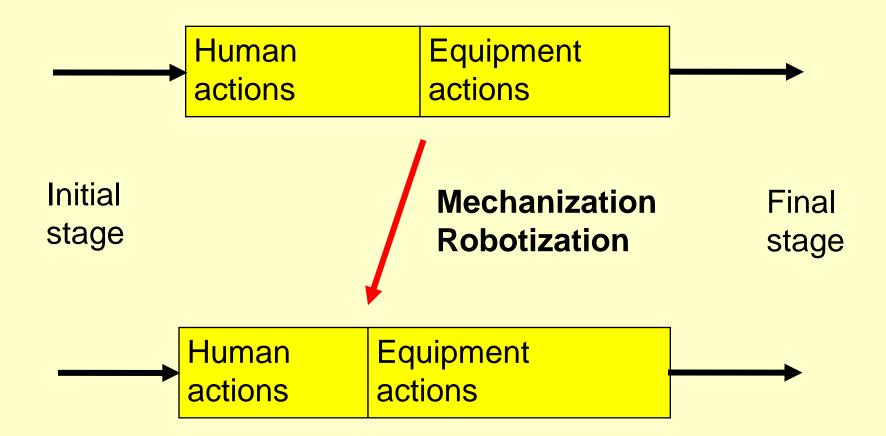




People & Equipment

Actions	People	Equipment
Provide strength and	Movement system:	Power tools:
energy	*muscles	*energy sources
	*lungs	*Transmissions
WALKING		WHEELCHAIR
Receive and issue	Senses:	Telecommunications tools:
Information	*eyes	*scanner
	*ears	*microphone
	*voice	*monitor
	*hands	*keyboard
DISCUSSION		HEARING AID
Make decisions	Thought system:	Computer equipment:
	*brain	*computer
	*memory	*software
		*artificial intelligence
TAKING MEDICINES		EQUIPMENT WITH ALARM

Mechanization & robotization concept



Lessons from the construction industry













Mechanization & robotization concepts in construction

Initial stage





Mixing sand and cement by a spade



Sand and cement are already mixed in the factory



Finishing a concrete floor





Assembling a wall panel



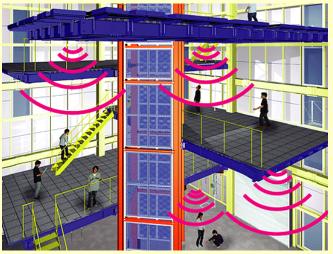
Mechanization & robotization concepts in housekeeping

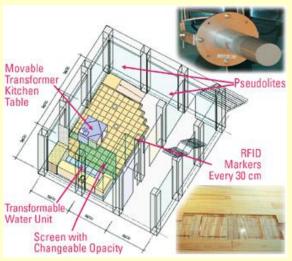
Initial stage		Final stage	
	Vacuum the house	Philips 19	Robot
	Playing with a puppet		Robot which reacts on voice
	Stepping stairs		Chair lift

House as a robot







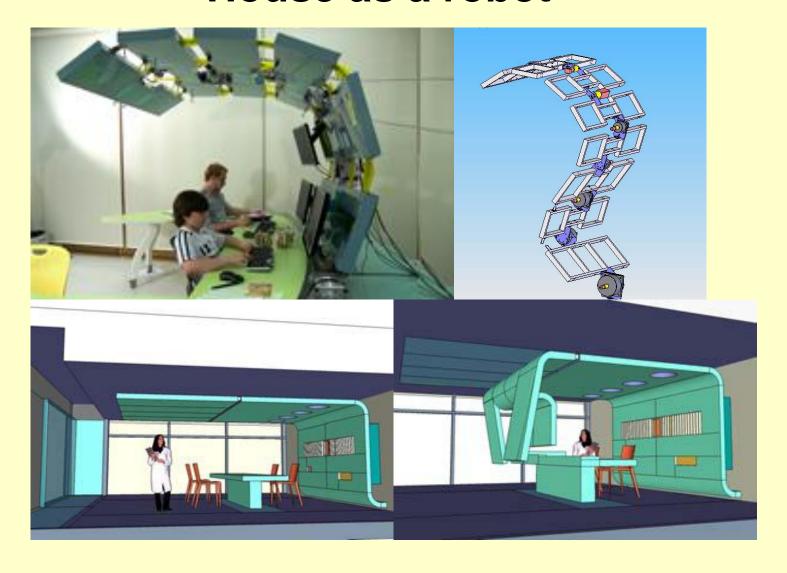




The **WABOT-HOUSE** laboratory in Japan is a symbiotic society where robots and human beings share the same sphere of living embraced by the natural environment. The detail shows a floor adaptable system.

14

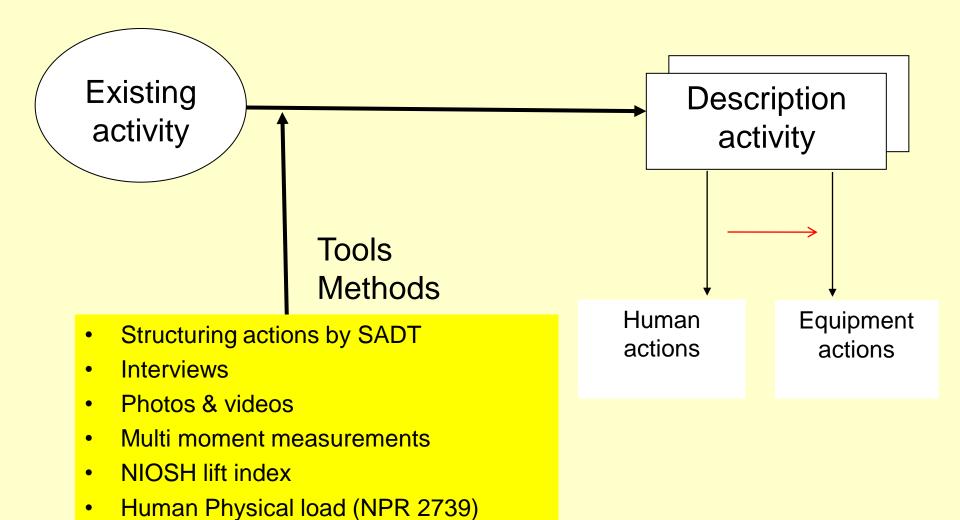
House as a robot



How to generate end-user values

- Analyzing activities and actions
- Collaborative design

Analyzing ADL



Analyzing peeling potatoes



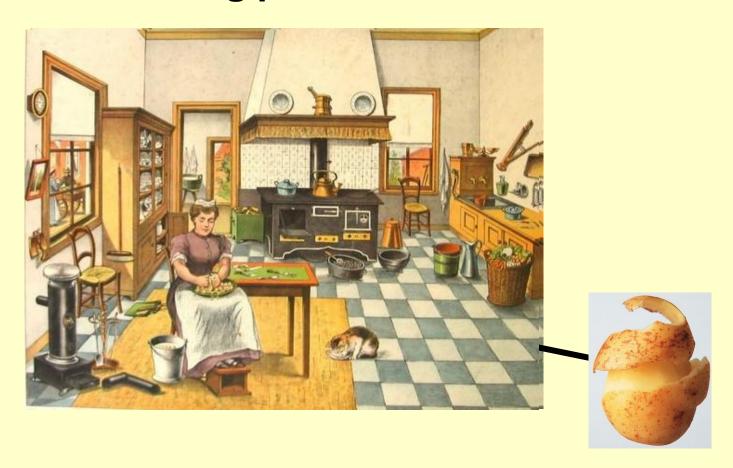






Exercise analyzing Activity Daily Living

Peeling potatoes



Analyzing activities

Initial stage





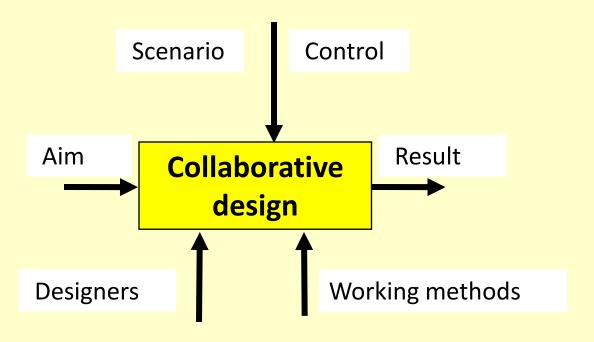
Sequence	Activity	Equipment used for the activity and describing its sub-activity.	Describing the sub-activities by people
1	Making the workplace ready	Chair: sitting Newspaper: peelings storage	Choosing a comfortable working place
2	Filling pan with water	Pan: to store peeled potatoes Tap: water supply	Handling tap and holding pan. Controlling the water flow.
3	Peeling	Knife: peeling the potato	Controlling peeling process Putting the peel on the newspaper

End stage

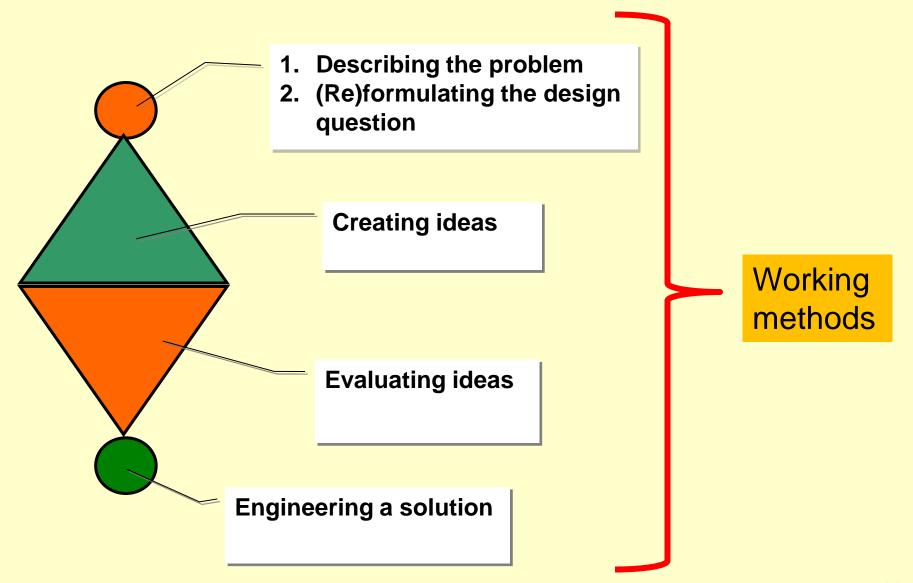




Collaborative design



Scenario collaborative design



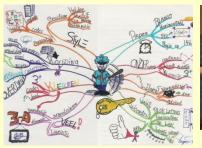
Ruimte maken met behulp van werkvormen





























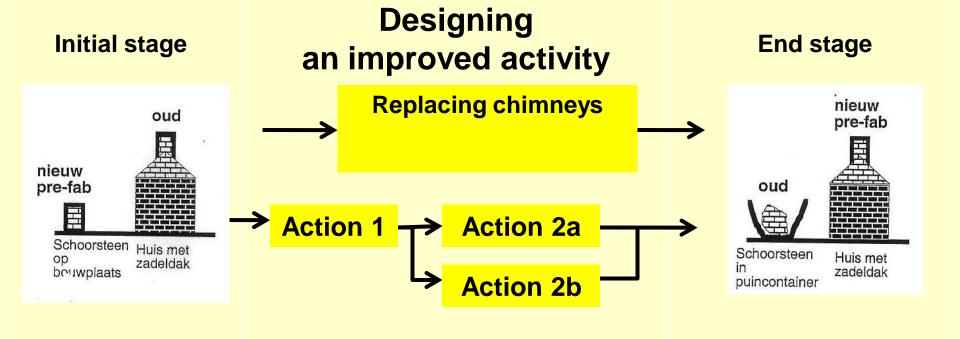












Characteristics initial stage

- Old chimney on the roof
- New chimney on the ground
- Pre fab chimney

Requirements

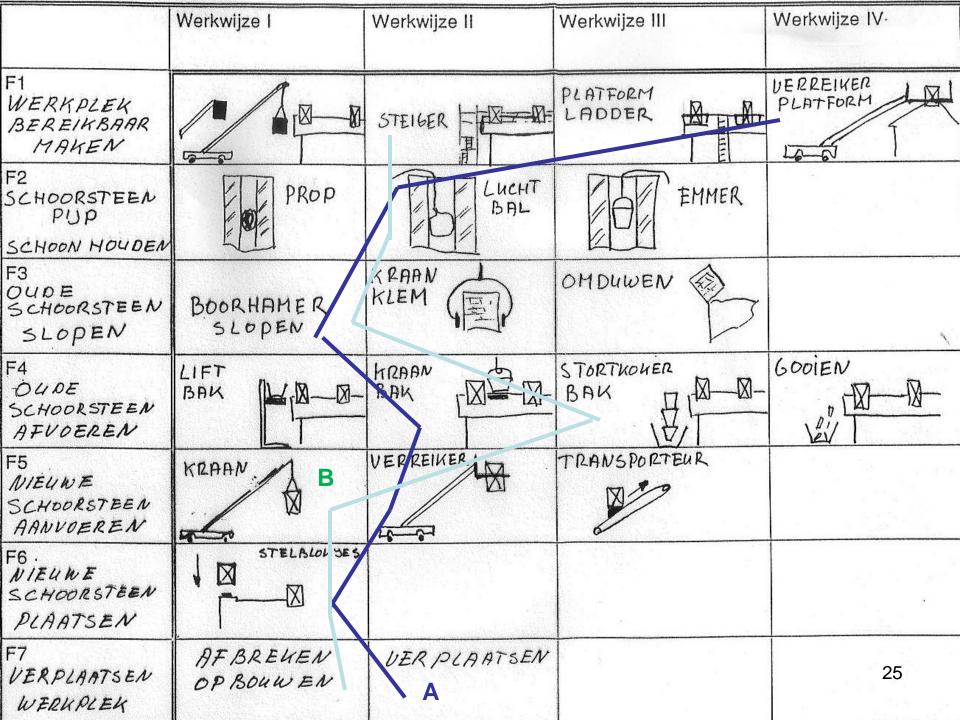
- Working method suitable for about 100 chimneys in one street
- 2. Maximum renovation time: four hour per chimney
- 3. Safe working place on the roof

Wishes

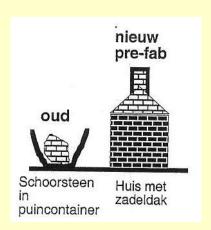
- 1. Minimal costs
- 2. Minimal time

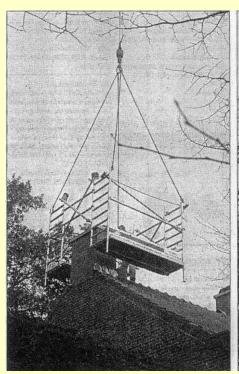
Characteristics end stage

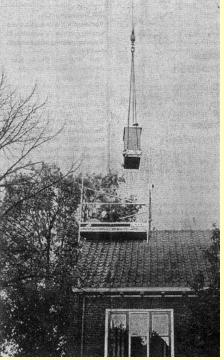
- •New chimney on the roof
- Demolished chimney in rubble container

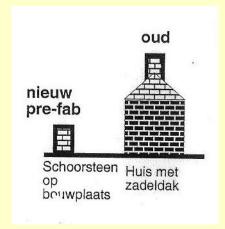


Solution in practice







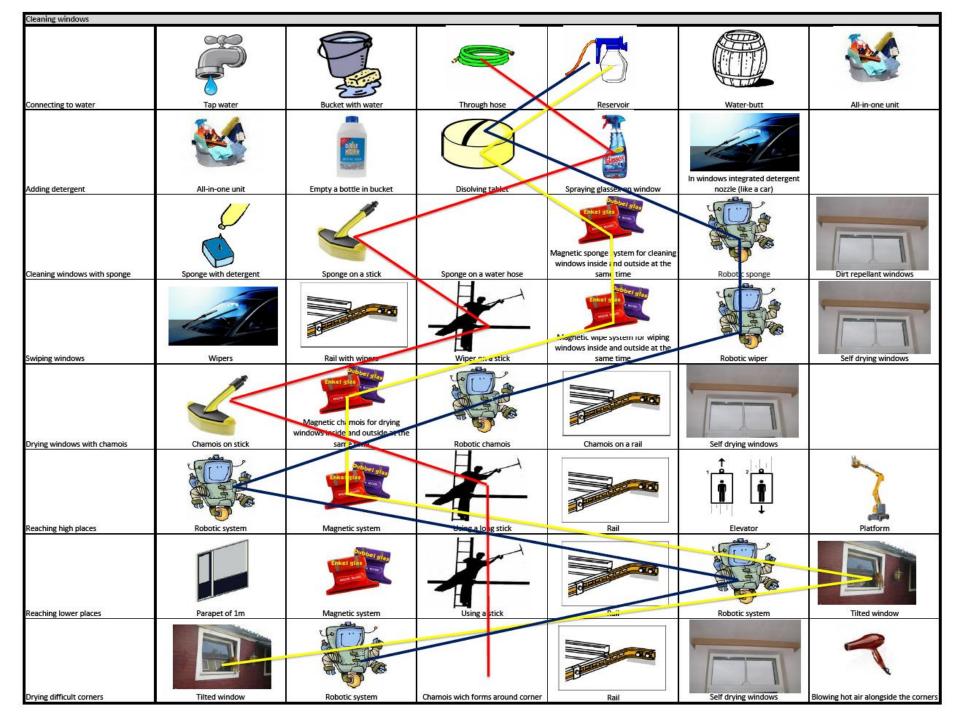


Conclusion

Select the suitable working methods to enhance end-user values

Questions?









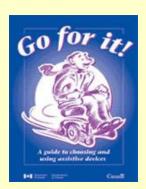


A humanoid robot named Chrome-kid picks up a tee-shirt from a laundry basket to fold it during the housekeeping robot contest in Kawasaki in Kanagawa prefecture, suburban Tokyo on August 17, 2008. 15 hand-made robots participated the preliminary competition and will be vying for the total prize of money 1 million yen in the final next month.

Architectural robots







http://www.youtube.com/watch?v=MjunOm0oLuA

http://www.youtube.com/watch?v=s1E3AtnlS5g

http://www.youtube.com/watch?v=-k2j2WKaMws

http://www.metacafe.com/watch/2395592/interactive_toilet_itoi_demonstration_video/

Form to report activities Washing hands

Initial stage Dirty hands, tablet of soap, water

Sequence	Activity	Equipment used for the activity and describing its subactivity.	Describing the sub- activities by people
1	Moisten the hands	Tap: delivering water	Turning on and off the tap
2	Soaping the hands	Tablet of soap: delivering soap	Rubbing the soap
3a			
3b			

End stage: Clean hands, dirty water

Activities of Daily Living (ADL)

The current model seeks to define 'what living means' (Roper et al, 2000, p15) and it breaks it down into the following categories:

- Maintaining a safe environment
- Breathing
- Eating and drinking
- Communication
- Elimination
- Washing and dressing
- Controlling temperature
- Mobilization
- Working and playing
- Expressing sexuality
- Sleeping
- Death and dying

Roper N., Logan W.W. & Tierney A.J. (2000). *The Roper-Logan-Tierney Model of Nursing: Based on Activities of Living*. Edinburgh: Elsevier Health Sciences. ISBN 0443063737.

http://books.google.co.uk/books?id=RJ21lkAZQQ4C.

Retrieved from "http://en.wikipedia.org/wiki/Roper-Logan-Tierney model of nursing"



VIDEO's

http://world.honda.com/ASIMO/

http://www.youtube.com/watch?v=gfVZnGiG-rw

http://www-robotics.usc.edu/?I=Robots:Movies

http://www.twarobotics.nl/

Mechanization & robotization ADL







ASIBOT is portable assistive robot for elderly and disease people bringing more freedom in daily tasks as eating, drinking, shaving, make up, tooth cleaning, etc. The robot is under experimentation in the National Hospital of Paraplegics in Toledo.





